

MODEL QUESTION PAPER ON

DIGITAL SIGNAL PROCESSING

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BRANCH :- IT (Vth Sem)

Q.1 :- Explain various properties of discrete time LTI system?

Q.2. obtain the convolution of the following sequences

$$x[n] = u[n]$$

$$h[n] = 2^n u[n]$$

Q.3. Explain various properties of Z Transform?

Q.4. By using partial fraction expansion method, find the inverse Z Transform of-

$$H(z) = \frac{-4 + 8z^{-1}}{1 + 6z^{-1} + 8z^{-2}}$$

Q.5. what is sampling theorem? Explain Interpolation method for reconstruction?

Q.6. Explain Aliasing?

Q.7. Determine the DFT of the sequence

$$x(n) = \begin{cases} 4 & \text{for } 0 \leq n \leq 2 \\ 0 & \text{otherwise} \end{cases}$$

Q.8. Compute the DFTs of the sequence

$$x(n) = \cos \frac{n\pi}{2} \text{ where } N=4 \text{ using}$$

DIF FFT Algorithm.

Q.9. Determine Direct form I & II for

$$H(z) = \frac{0.28z^2 + 0.319z + 0.04}{0.5z^3 + 0.3z^2 + 0.17z - 0.2}$$

Q.10. Explain IIR filter design by the Bilinear Transformation?

Q1

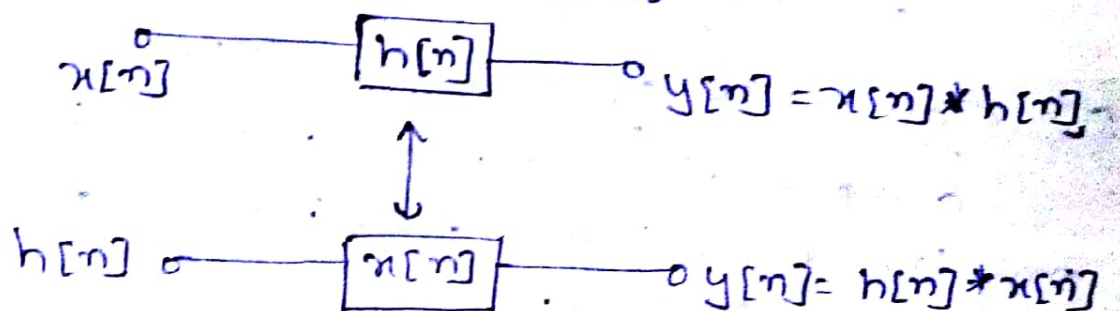
Ans: - Properties of LTI System

① The Commutative Property: -

According to commutative property the output of LTI system is

$$y[n] = x[n] * h[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k]$$

$$y[n] = h[n] * x[n] = \sum_{k=-\infty}^{\infty} h[k] x[n-k]$$



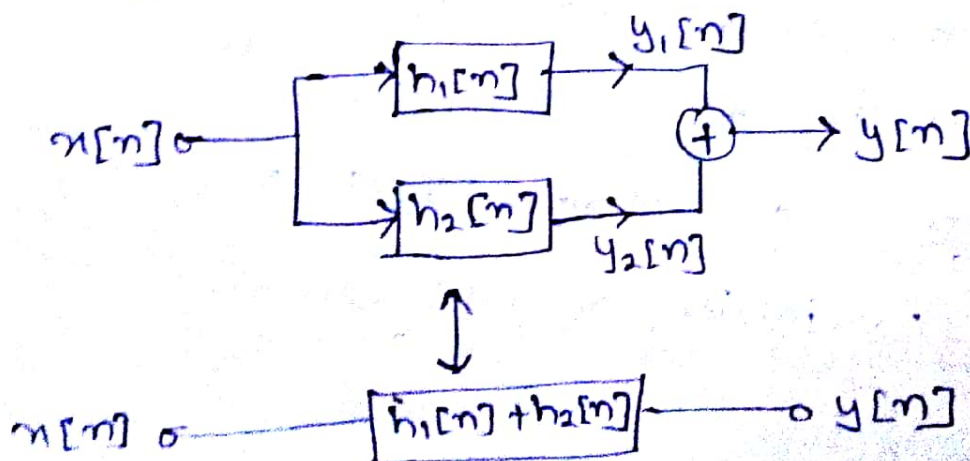
② The Distributive Property: -

According to this property

$$y[n] = x[n] * [h_1[n] + h_2[n]]$$

or

$$y[n] = x[n] * h_1[n] + x[n] * h_2[n]$$

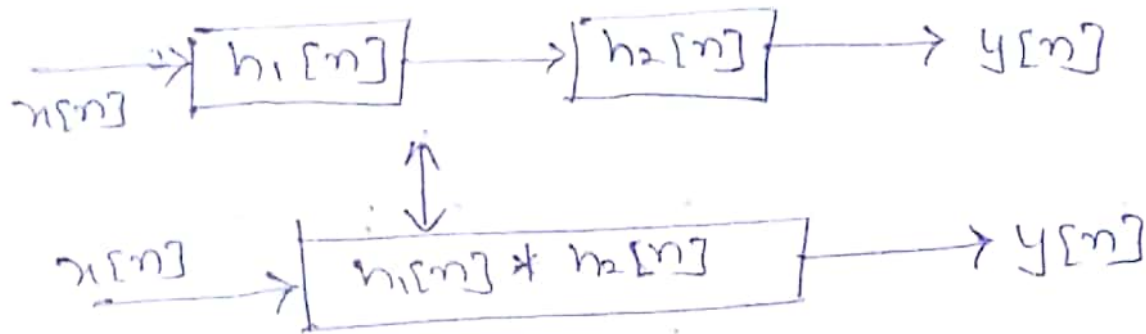


③ Associative property of LTI System: -

According to this property

$$y[n] = x[n] * [h_1[n] * h_2[n]]$$

$$y[n] = x[n] * h_1[n] * h_2[n]$$



④ Causality of LTI System: -

output of a causal system depends only on the present and past values of the input to the system.

LTI system is causal if its impulse response $h[n]$ is zero for $n < 0$.

$$y[n] = x[n] * h[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k]$$

$$y[n] = h[n] * x[n] = \sum_{k=0}^{\infty} h[k] x[n-k]$$

⑤ Static and Dynamic LTI System: -

⑥ Stability of LTI System

⑦ Static and Dynamic LTI System

⑧ Invertibility of LTI System:

Q.2

Ans: - Since $x[n] = 0$ for $n < 0$
& $h[n] = 0$ both are causal.

So

$$y[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k]$$

$$= \sum_{k=0}^n u[k] 2^{n-k} u[n-k]$$

$$y[n] = \sum_{k=0}^n 2^{n-k}$$

$$y[n] = 2^n \sum_{k=0}^n 2^{-k}$$

$$y[n] = 2^n [1 + 2^{-1} + 2^{-2} + \dots \text{(n+1) terms}]$$

$$y[n] = 2^{n+1} \left[1 - \left(\frac{1}{2}\right)^{n+1} \right]$$

$$y[n] = 2 \cdot 2^n - 1 \quad \text{for } n \geq 0$$

$$\text{or } y[n] = 2(2)^n u[n] - \underline{\underline{u[n]}}$$

Q.3

Ans: - Properties of Z Transform

(1) Linearity: - if $x_1(n) \xrightarrow{Z} X_1(z)$
& $x_2(n) \xrightarrow{Z} X_2(z)$

then

$$x(n) = a_1 x_1(n) + a_2 x_2(n) \xrightarrow{Z} X(z) = a_1 X_1(z) + a_2 X_2(z)$$

② Time Reversal: -

$$\text{if } x(n) \xleftrightarrow{z} X(z) \\ \text{then } x(-n) \xleftrightarrow{z} X(z^{-1})$$

③ Time shifting: -

$$\text{if } x(n) \xleftrightarrow{z} X(z) \text{ then} \\ x(n-k) \xleftrightarrow{z} z^{-k} X(z)$$

④ Scaling: -

$$\text{if } x(n) \xleftrightarrow{z} X(z) \text{ then} \\ a^n x(n) \xleftrightarrow{z} X(a^{-1}z)$$

⑤ Differentiation: -

$$\text{if } x(n) \xleftrightarrow{z} X(z) \text{ then} \\ nx(n) \xleftrightarrow{z} -z \frac{dX(z)}{dz} \text{ or } z^{-1} \frac{dX(z)}{dz}$$

⑥ Convolution: -

$$\text{if } x_1(n) \xleftrightarrow{z} X_1(z) \\ \& x_2(n) \xleftrightarrow{z} X_2(z)$$

$$\text{then } x(n) = x_1(n) * x_2(n) \xleftrightarrow{z} X(z) = X_1(z) X_2(z)$$

⑦ Initial value Theorem: -

if $x(n)$ is causal system

$$\text{then } x(0) = \lim_{n \rightarrow 0} x(n) = \lim_{|z| \rightarrow \infty} X(z)$$

⑧ Final value Theorem: -

$$x(\infty) = \lim_{n \rightarrow \infty} x(n) = \lim_{|z| \rightarrow 1} [(1-z^{-1})X(z)]$$

Q.4.

Ans. -

$$H(z) = \frac{-4 + 8z^{-1}}{1 + 6z^{-1} + 8z^{-2}} = \frac{-4 + 8z^{-1}}{(1 + 4z^{-1})(1 + 2z^{-1})}$$

$$H(z) = \frac{A_1}{1 + 4z^{-1}} + \frac{A_2}{1 + 2z^{-1}}$$

$$A_1 = \left. \frac{-4 + 8z^{-1}}{1 + 2z^{-1}} \right|_{z^{-1} = -1/4} = \frac{-6}{1/2} = -12$$

$$A_2 = \left. \frac{-4 + 8z^{-1}}{1 + 4z^{-1}} \right|_{z^{-1} = -1/2} = \frac{-8}{-1} = 8$$

$$H(z) = \frac{-12}{1 + 4z^{-1}} + \frac{8}{1 + 2z^{-1}}$$

→ taking inverse Z Transform

$$h(n) = [-12(-4)^n + 8(-2)^n] u(n)$$

Q.5.

Ans. - Sampling theorem:

For perfect reconstruction of a continuous-time signal from its samples, the sampling rate or sampling frequency should be greater than or equal to Nyquist rate of the message signal.

$$\boxed{f_s \geq 2f_m}$$

Interpolation Techniques:

It is a procedure for reconstructing a continuous time signal from its sample values.

Let a spectrum of reconstructed signal from its samples $S_r(t)$

$$S_r(t) = S_p(t) * h(t) \quad (1)$$

$h(t)$ - Impulse response of low pass filter
 $S_p(t)$ is given as

$$S_p(t) = \sum_{n=-\infty}^{\infty} S(nT_s) \delta(t - nT_s)$$

from (1)

$$S_r(t) = \sum_{n=-\infty}^{\infty} S(nT_s) \delta(t - nT_s) * h(t)$$

$$S_r(t) = \sum_{n=-\infty}^{\infty} S(nT_s) h(t - nT_s) \quad (2)$$

Impulse response of low pass filter is given by

$$h(t) = \omega_c T_s \frac{\sin(\omega_c t)}{\pi \omega_c T_s}$$

So from (2)

$$S_r(t) = \sum_{n=-\infty}^{\infty} S(nT_s) \left[\frac{\omega_c T_s \sin[\omega_c (t - nT_s)]}{\pi \omega_c (t - nT_s)} \right]$$

Q.6

Ans: Aliasing phenomenon is caused under sampling. It occurs when sampling rate $[W_s < 2W_{max}]$.

A phenomenon of high frequency components in a spectrum of a continuous time signal seemingly taking on the identity of a lower freq. in the spectrum of its sampled version

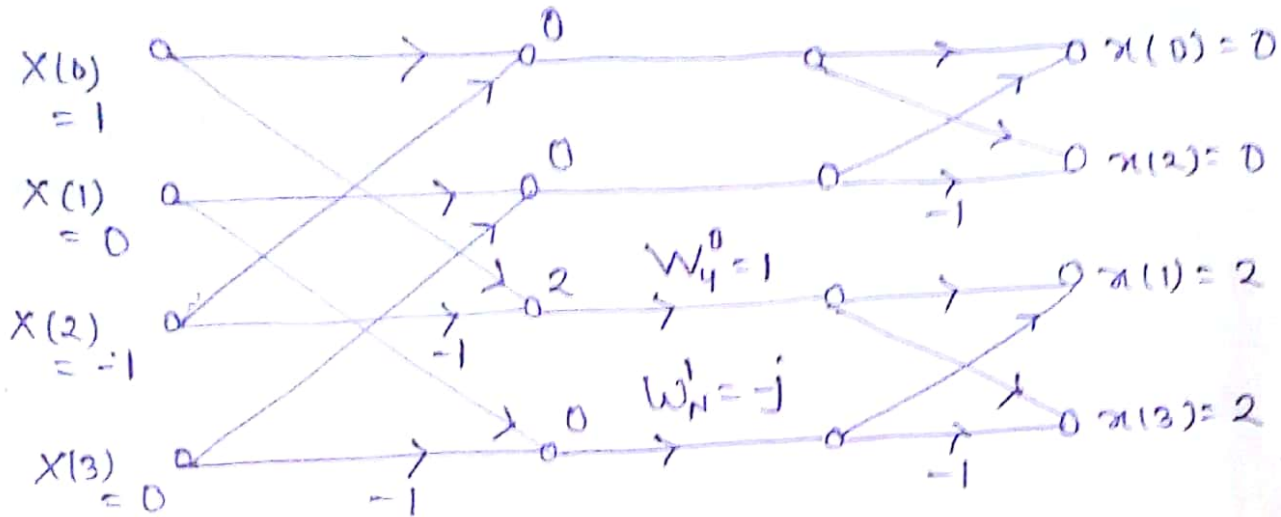
Q. 8.

Ans: -

given $N = 4$ and $x(n) = \{1, 0, -1, 0\}$

$$w_N^k = e^{-j(2\pi/N)k}$$

$$w_4^0 = 1 \quad \text{and} \quad w_4^1 = e^{-j\pi/2} = -j$$



Q. 7

Ans: -

N point DFT

$$X(k) = \sum_{n=0}^{N-1} x(n) e^{-j2\pi nk/N}, \quad k = 0, 1, \dots, N-1$$

$$x(n) = \left(\frac{1}{4}, \frac{1}{4}, \frac{1}{4}\right)$$

Therefore $X(k) = \frac{1}{4} [1 + e^{-j\omega} + e^{-j2\omega}] \Big|_{\omega = \frac{2\pi k}{N}}$

$$= \frac{1}{4} e^{-j\omega} [1 + 2 \cos \omega]$$

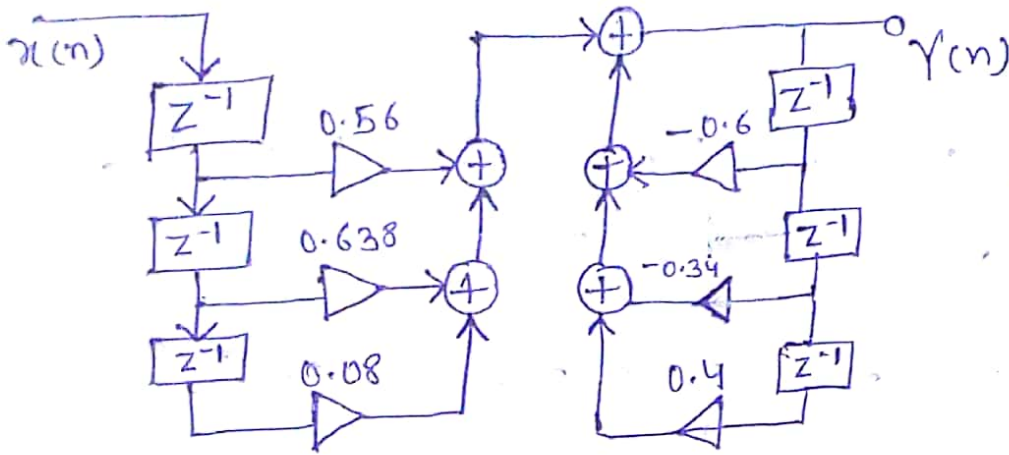
$$= \frac{1}{4} e^{-j2\pi k/3} \left[1 + 2 \cos \left(\frac{2\pi k}{3}\right)\right]$$

$$k = 0, 1, \dots, N-1$$

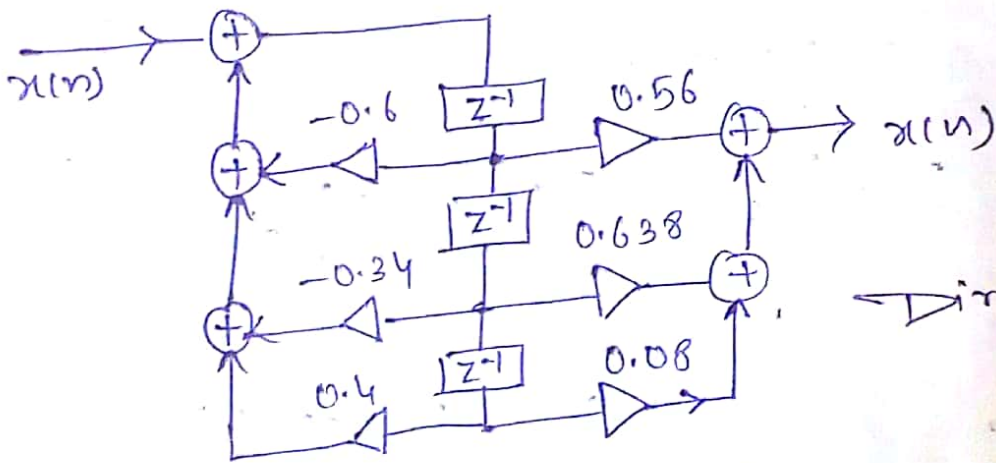
Q.9

Ans: -

$$H(z) = \frac{0.56z^{-1} + 0.638z^{-2} + 0.08z^{-3}}{1 + 0.6z^{-1} + 0.34z^{-2} + 0.4z^{-3}}$$



Direct form I



Direct form II

Q.10

Ans: -

Let the system function of the Analog filter be

$$H(s) = \frac{b}{s+a} \quad \text{--- (1)}$$

$$H(s) = \frac{Y(s)}{X(s)} = \frac{b}{s+a}$$

$$sY(s) + aY(s) = bX(s)$$

Taking inverse Laplace Transform

$$\frac{dy(t)}{dt} + ay(t) = bx(t) \quad - (2)$$

By Trapezoidal Rule

$$\int_{nT-T}^{nT} a(t) dt = \frac{T}{2} [a(nT) + a(nT-T)] \quad - (3)$$

integrate Eqⁿ (2) b/w limits $(nT-T)$ & nT
& apply Trapezoidal Rule

$$y(nT) - y(nT-T) + \frac{aT}{2} y(nT) + \frac{aT}{2} y(nT-T) \\ = \frac{bT}{2} x(nT) + \frac{bT}{2} x(nT-T)$$

Taking Z Transform

$$H(z) = \frac{Y(z)}{X(z)} = \frac{b}{\frac{2}{T} \left(\frac{1-z^{-1}}{1+z^{-1}} \right) + a} \quad - (4)$$

Compare (1) & (4)

$$S = \frac{2}{T} \left(\frac{1-z^{-1}}{1+z^{-1}} \right) = \frac{2}{T} \left(\frac{z-1}{z+1} \right)$$

By putting S value in any analog filter, can be converted into digital IIR filter